

UNIVERSITY OF LONDON

GOLDSMITHS COLLEGE

Department of Computing

B. Sc. Examination 2018

IS52038A/B

Algorithms & Data Structures

Duration: 2 hours 15 minutes

Date and time:

This paper is in two parts: part A and part B. You should answer ALL questions from part A and TWO questions from part B. Part A carries 40 marks, and each question from part B carries 30 marks. The marks for each part of a question are indicated at the end of the part in [.] brackets.

There are 100 marks available on this paper.

Calculators may be used in this examination; however, calculators which display graphics, text or algebraic equations are not allowed.

**THIS PAPER MUST NOT BE REMOVED
FROM THE EXAMINATION ROOM**

Part A
Attempt all questions

Question 1

(a) Define the term *implicit data structure*, and give one example of an implicit data structure. [3]

(b) A queue Q is initially empty, and then undergoes the following sequence of operations:

- 1: ENQUEUE($Q, 34$)
- 2: $x \leftarrow$ DEQUEUE(Q)
- 3: ENQUEUE($Q, 35$)
- 4: ENQUEUE(Q, x)
- 5: $x \leftarrow$ DEQUEUE(Q)

Illustrate the state of the variables and data structures after *each* step of this sequence. (you can assume that the variable x initially has the value 0.) [5]

(c) Write in pseudocode an algorithm to compute and return the n th term of the series u_n , where $u_0 = 1$, $u_1 = 3$ and $u_{k+2} = 2 \times u_{k+1} - u_k$. [5]

(d) In order to sort a linear collection of size N , a divide-and-conquer sorting algorithm performs three sorts of one-third the size, followed by work to combine the three results that is proportional to N .

i. Write down the recurrence relation that expresses $T(N)$, the time to sort a collection of size N , in terms of the time to sort smaller collections and the time to combine the results. [2]

ii. Draw the recursion tree to illustrate your answer to part d.(i). [3]

iii. As precisely as possible, give the complexity of this divide-and-conquer sorting algorithm in terms of the size N . [3]

(e) The following SELECT function returns the k^{th} biggest element from the array A .

Require: A :: array of non-negative integers

Require: k :: positive integer

Require: $\text{LENGTH}(A)$ k

```
1: function SELECT( $A, k$ )
2:    $S \leftarrow$  new Vector( $k$ )
3:    $L \leftarrow$   $\text{LENGTH}(A)$ 
4:   for  $0 \leq i < k$  do
5:      $S[i] \leftarrow 0$ 
6:   end for
7:   for  $0 \leq i < L$  do
8:      $v \leftarrow A[i]$ 
9:     for  $0 \leq j < k$  do
10:      if  $v \mathbf{O} S[j]$  then
11:         $\text{tmp} \leftarrow S[j]; S[j] \leftarrow v; v \leftarrow \text{tmp}$ 
12:      end if
13:       $S[i] \leftarrow v$ 
14:    end for
15:  end for
16:  return  $S[k-1]$ 
17: end function
```

- i. What should operator \mathbf{O} (on line 10) be for SELECT to correctly return the k^{th} biggest element? [2]
- ii. With what arguments should select be called to retrieve the median element of A ? (you can assume that the length of A is odd.) [2]
- iii. How many times do each of line 5 and line 11 execute in the worst case? (express your answers in terms of the argument k and the length of the array L) [3]
- iv. What is the worst-case running time complexity for computing the median of a collection of numbers using this approach? (express your answer using Θ notation). [2]

(f) The directed graph G has a vertex set

$$V = \{A, B, C, D\}$$

and edge list

$$E = \{(A, B), (B, C), (C, D), (D, A), (D, B), (D, C), (D, D)\}$$

- i. Construct the adjacency matrix for the graph G . [4]
- ii. How many paths of length 2 are there from vertex D to itself? Justify your answer. [2]

- (g) The function $f(N)$ is proportional to $\log(N)$, while the function $g(N)$ is proportional to N . Copy and complete the following table of values for the functions $f(N)$ and $g(N)$ and hence, or otherwise, determine approximately the value of N for which $f(N) = g(N)$.

[4]

N	$f(N)$	$g(N)$
2	5	1
4		
8		
16		
32		
64		

Part B

Attempt two questions

Question 2

- (a) Describe two possible implementations of strings, and specify as precisely as you can the computational complexity for the LENGTH operation in terms of the number of characters N for each implementation. [3]
- (b) Draw the compressed trie representing the set of strings { “called”, “allied”, “carted”, “allies” }. [4]
- (c) Describe in detail the sequence of operations on the compressed trie to determine that:
- string allied is present in the set; [3]
 - string call is not present in the set. [3]
- (d) State the precise worst-case number of character comparisons done in naïve string matching searching for a pattern of size m in a text of size n . Justify your answer, for example by means of a diagram or pseudocode. [3]
- (e) The following pseudocode computes the edit distance between two strings.

```
function EDITDISTANCE( $s_1, s_2$ )  
    return D( $s_1, s_2, \text{LENGTH}(s_1), \text{LENGTH}(s_2)$ )  
end function
```

```
function D( $s_1, s_2, i, j$ )  
    if  $j = 0$  then  
        return  $i \times a$   
    else if  $i = 0$  then  
        return  $j \times b$   
    else if  $s_1[i-1] = s_2[j-1]$  then  
        return D( $s_1, s_2, i-1, j-1$ )  
    else  
         $d_1 \leftarrow a + D(s_1, s_2, i-1, j)$   
         $d_2 \leftarrow b + D(s_1, s_2, i, j-1)$   
         $d_3 \leftarrow c + D(s_1, s_2, i-1, j-1)$   
        return MIN( $d_1, d_2, d_3$ )  
    end if  
end function
```

Describe the meanings of the parameters a , b and c in the algorithm. [4]

- (f) i. Describe how you would adapt the algorithm described above to have it use dynamic programming. [4]
- ii. State how your adaptation changes the time and space complexity of the algorithm. [2]

- (g) For a particular application, the parameters are set as follows: $a = 1$, $b = 2$ and $c = 2$. Compute the result of `EDITDISTANCE("acre", "mace")`, showing your working. [4]

Question 3

- (a) The following pseudocode inserts a new item into a binary max-heap.

```
Require: H :: a binary heap
function INSERT(H,k)
    heap[H.heapsize] ← k
    i ← H.heapsize
    H.heapsize ← H.heapsize + 1
    while i > 0 ∧ H[PARENT(i)] < H[i] do
        SWAP(H[i],H[PARENT(i)])
        i ← PARENT(i)
    end while
end function
```

Justify the statement “insertion into a binary heap takes time in $\Theta(\log N)$ ” [3]

- (b) Write pseudocode for constructing a new heap by inserting elements from an array one-at-a-time. (you can call the above INSERT function within your own algorithm.) [3]
- (c) Argue that constructing a binary max-heap by inserting items one-by-one has worst case time complexity in $\Theta(N \log N)$. Illustrate your argument with an example of worst-case behaviour. [5]
- (d) Describe BUILDHEAP, the algorithm for constructing a max-heap from an array in-place, with time complexity in $\Theta(N)$, as precisely as you can. (you may wish to use pseudocode and/or diagrams in your answer.) [4]
- (e) What are the final contents of the binary heap after running BUILDHEAP on the array [1 3 7 2 8 4 5 9]? [4]
- (f) For the hash function $f(x) = 17x+13$ and the reduction function $g(x) = x \bmod 10$, draw the contents of a hash table with 10 buckets after inserting (in this order) { 2, 5, 12 }, assuming collision resolution by linear probing. [3]
- (g) What would the contents of the hash table be using the Robin Hood linear probing variant? [3]
- (h) Explain the benefits of Robin Hood linear probing over the standard linear probing variant. (you may wish to refer to your answers to parts (f) and (g).) [5]

Question 4

- (a) The following pseudocode operates on a linked list, and is intended to return a new list containing the positive elements only.

```

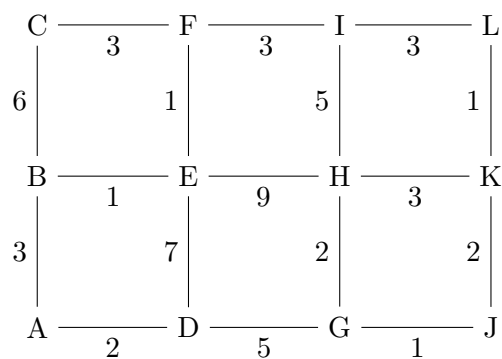
function A(L)
  if FIRST(L) > 0 then
    return CONS(FIRST(L), A(REST(L)))
  else
    return A(REST(L))
  end if
end function

```

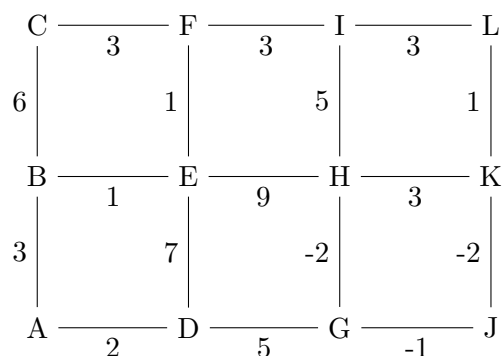
What is missing from this algorithm? Write out a corrected algorithm. [4]

- (b) Write pseudocode for a function that returns the sum of all the odd integers in a list. (you can assume that the list contains only integers, but you must define how you distinguish odd integers explicitly.) [5]

- (c) For the following graph, execute Dijkstra's algorithm to find the shortest path between B and K, showing your working. [9]



- (d) Explain why the following graph has no shortest-path between B and K. [3]



- (e) Explain how a suitable heuristic for the distance between the current node and the destination node leads to the A* algorithm. Give one heuristic that is commonly used with the A* algorithm. [6]
- (f) “Dijkstra’s algorithm can be thought of as the A* algorithm with a particular choice of heuristic”. Justify this statement. [3]