UNIVERSITY OF LONDON

GOLDSMITHS COLLEGE

Department of Computing

B. Sc. Examination 2014

IS52017B (Resit) **Algorithms and Complexity Theory**

Duration: 2 hours 15 minutes

Date and time:

Answer all four questions

THIS PAPER MUST NOT BE REMOVED FROM THE EXAMINATION ROOM

- (a) i. Define mathematically and formally what it means for an array a of N integers to be sorted in ascending order.
 - ii. In order to sort a list of objects of type T what property must the elements of type T have?
 - iii. Give two different orderings on Strings and say how your two definitions would cause the array of Strings {"dogs", "cat", "person"} to be sorted in ascending order?

[9]

[8]

- (b) Describe how the *merge sort* algorithm works. When doing this, do not give the algorithm for merging but informally specify what the *merge* algorithm should do and give an example.
- (c) Here is a method for merging two sorted lists used in Merge Sort:

```
static int [] merge( int[] a, int [] b)
{
  int N=a.length+b.length;
  int [] c = new int[N];
  int i=0,j=0,k=0;
  while (i<a.length && j <b.length)
  {
    if (a[i] < b[j]) {c[k]=a[i];i++;}
    else {c[k]=b[j];j++;}
    k++;
}
  if (i==a.length) for(int z=j;z<b.length;z++) c[a.length+ z] =b[z];
  else for(int z=i;z<a.length;z++) c[b.length+ z] =a[z];
  return c;
}</pre>
```

What would happen is we applied it to two non-sorted arrays? For example if $c=\{1,3,2\}$ and $d=\{2,1,5\}$. What would merge (c,d) return? [8]

(a) Let $x = 2^y$ Which of the following is true:

i.
$$y = log_e(x)$$

ii.
$$y = log_2(x)$$

iii.
$$x = log_2(y)$$

iv. None of the above.

[2]

(b) Which of the following functions will produce the largest values (asymptotically) as N gets bigger:

i.
$$f(N) = 30 * N$$

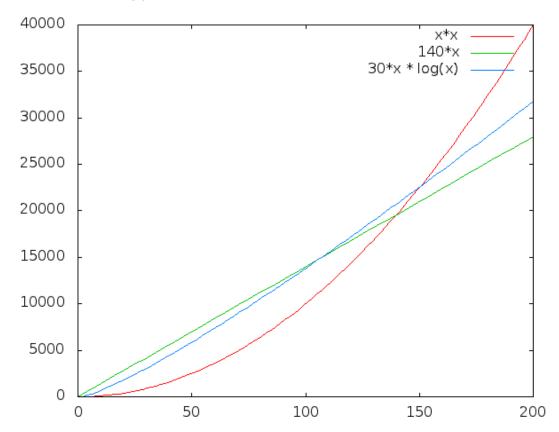
ii.
$$f(N) = N^2$$

iii.
$$f(N) = N * log(N)$$

iv. None of the above.

[2]

(c) Consider the following plot:



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What is the equation of the middle curve in the plot. i.e. the one which has the value of just over 30000 when x has the value 200?

```
i. x * x
```

ii. 140 * x

iii. 30 * x * log(x)

iv. None of the above.

[2]

(d) The time complexity of insertion sort is

```
i. O(N)
```

- ii. $O(N^2)$
- iii. O(N * log(N))
- iv. None of the above.

[2]

(e) The time complexity of merge sort is

```
i. O(N)
```

- ii. $O(N^2)$
- iii. O(N * log(N))
- iv. None of the above.

[2]

- (f) If it take 5 nanoseconds to sort 10 elements using insertion sort, roughly how long will it take to sort 20 elements?
 - i. 10 nanoseconds
 - ii. 20 nanoseconds
 - iii. 30 nanoseconds
 - iv. None of the above.

[2]

(g) What is the time-complexity of this function in terms of N?

```
int f(int N)
{
  int total=0;
  for (int i=0;i<N;i++)
    for (int j=0;j<N;j++)</pre>
```

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```
total=total+i+j;
     return total;
   }
    i. linear
    ii. quadratic
   iii. exponential
   iv. None of the above.
                                                                                   [2]
(h) What is the time-complexity of this function in terms of N?
   int f(int N)
     if (N<2) return 1;
     return f(N-1)+f(N-2);
   }
    i. linear
    ii. quadratic
   iii. exponential
   iv. None of the above.
                                                                                   [2]
(i) Here are two methods for computing x^n:
   static int powerA(int x, int n)
         int total=0;
         while (n>0) {total=total*x;n--;}
         return total;
   }
   static int powerB(int x, int n)
         if (n==0) return 1;
         int k=n/2;
         int z=powerB(x,k);
         int r=z*z;
         if (n\%2==0) return r;
```

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```
return x*r;
}
```

Which one of the following is true

- i. powerA is linear and powerB has quadratic time-complexity.
- ii. powerA is exponential and powerB has log(N) time-complexity.
- iii. powerA is quadratic and powerB has exponential time-complexity.
- iv. None of the above.

[2]

```
(j) Here are two methods for computing x^n:
```

```
static int powerA(int x, int n)
{
    int total=0;
    while (n>0) {total=total*x;n--;}
    return total;
}

static int powerB(int x, int n)
{
    if (n==0) return 1;
    int k=n/2;
    int z=powerB(x,k);
    int r=z*z;
    if (n%2==0) return r;
    return x*r;
}
```

Which one of the following is true

- i. powerA is more efficient than powerB.
- ii. powerB is more efficient than powerA.
- iii. powerB has the same efficiency as powerA.
- iv. None of the above.

[2]

(k) Write a method whose heading is

```
HashMap <String,Integer> occurrences (ArrayList <String> x)
```

which returns a HashMap, mapping each String s in x to the number of occcurences of s in x.

[5]

- (a) i. What is a *spanning tree* of a Graph? Give an example.
 - ii. What is the purpose of Dijkstra's Algorithm? Give an example where it could be used in practice.
 - iii. What is the purpose of Prim's Algorithm? Give an example where it could be used in practice.

[9]

- (b) Prove that if $v_1 \to v_2 \to w_1 \to \ldots \to w_m \to v_n$ is a shortest path between v_1 and v_n in a graph G then $v_2 \to w_1 \to \ldots \to w_m \to v_n$ is a shortst path between v_2 and v_n in G.
- (c) Given the abstract class abstractGraph below, for undirected graphs whose vertices are of type T, write a method, which calls the abstract methods in abstractGraph which returns the set of all isolated vertices in the graph. An isolated vertex is one with no neighbours.

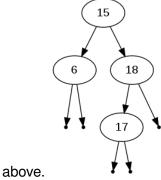
```
public abstract class abstractGraph <T>
{
   public abstract Set <T> neighbours(T v); // the set of neighbours of vertex v
   public abstract Set <T> vertices(); // the set of all vertices in the graph
}
```

[8]

(a) A Binary Tree whose nodes of type T can be defined as follows:

```
empty \in BT[T]
consBT: T \times BT[T] \times BT[T] \rightarrow BT[T]
```

i. Construct the following tree using the above functions empty and consBT



[3]

ii. Consider the following Java classes:

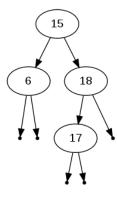
```
public abstract class binaryTree <T>
}
class emptyTree <T> extends binaryTree <T>
}
class consbinaryTree <T> extends binaryTree <T>
{
   T root;
   binaryTree <T> left;
   binaryTree <T> right;
    consbinaryTree (T roo, binaryTree <T> 1, binaryTree <T> r)
    {root=roo;left=l;right=r;}
}
```

What is the Java expression that generates the binary tree:

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[3]

(b) The depth function on binary trees is defined as follows:

$$depth: BT[T] o \mathbb{N}$$

$$depth(empty) = 0$$

$$depth(consBT(x,b_1,b_2)) = 1 + max(depth(b_1), depth(b_2))$$

- i. Define a *depth* method for the class binaryTree <T>.
- ii. Define a *depth* method for the class emptyTree <T>.
- iii. Define a *depth* method for the class consbinaryTree <T>. You may assume the existence of a max method.

[6]

(c) The functions *left* and *right* on BT[T] are of the following types:

$$\begin{aligned} \textit{root} : \textit{BT}[T] &\to T \\ \textit{left} : \textit{BT}[T] &\to \textit{BT}[T] \\ \textit{right} : \textit{BT}[T] &\to \textit{BT}[T] \end{aligned}$$

and satisfy the following axioms:

$$\mathit{root}(\mathit{consBT}(x,b_1,b_2)) = x$$
 $\mathit{left}(\mathit{consBT}(x,b_1,b_2)) = b_1$ $\mathit{right}(\mathit{consBT}(x,b_1,b_2)) = b_2$

- i. Define methods *left* and *right* for the class binaryTree <T>.
- ii. Define methods *left* and *right* for the class consbinaryTree <T>.

[4]

(d) Write a method whose heading is
 static Integer least(BT <Integer> b)
 which returns the smallest element of a non-empty Binary Search Tree b of Integers. (Assume the existence of an isEmpty() method on binary trees.)

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END OF EXAMINATION